## UNCOMPUTABILITY AND COMPLEXITY OF QUANTUM CONTROL

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D.I. Bondar, A.N. Pechen, Uncomputability and complexity of quantum control, arXiv:1907.10082

## STRUCTURE

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- (Un)computability
- Diophantine equations
- Quantum control: overview
- Digitizes quantum control
- Result

### ALGORITHMS

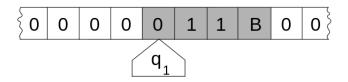
### Muhammad ibn Musa al-Khwarizmi (780–850)



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## TURING MACHINE<sup>1</sup>





<sup>1</sup>A.M. Turing, On computable numbers, with an application to the Entscheidungsproblem, Proceedings of the London Mathematical Society, 2, 42 (1), pp. 230–65 (1936) (published 1937).)

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**The halting problem:** determine, from a description of an arbitrary computer program and an input, whether the program will finish running, or continue to run forever.

**Theorem:** The HP is undecidable over Turing machines.

#### "Proof"

- $T_1, T_2, \ldots, -$  algorithms which have as input and output natural numbers.
- Suppose there exist algorithm A(N, X):
  - halts and returns 1 if  $T_N(X)$  does not halt
  - does not halt otherwise
- Then D(N) = A(N, N) halts iff  $T_N(N)$  does not halt.

•  $D = T_K : D(K) = A(K, K)$  halts if D(K) does not halt. Contradiction!

# DIOPHANTINE EQUATIONS

Diophantine equations are polynomial equations with *integer* coefficients and *integer* solutions:

$$D(x_1,\ldots,x_n)=0$$



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#### Examples:

- $x^2 ny^2 = 1$  (Pell's eq.): (1,0) and  $(x, y) : x/y \sim \sqrt{n}$
- $x^2 + y^2 = z^2$  (Pythagorean triples): (3,4,5), (5,12,13), ...
- $x^n + y^n = z^n$  for n > 2 (Fermat's Last Theorem): not solvable

## HILBERT'S 10TH PROBLEM



Find an algorithm which can determine whether a given Diophantine equation is solvable.

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## HILBERT'S 10TH PROBLEM



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**NO!** (Yuri Matiyasevich, Julia Robinson, Martin Davis, Hilary Putnam)



### UNCOMPUTABLE PROBLEMS IN QUANTUM PHYSICS

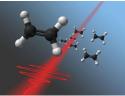
Diophantine equation  $D(x_1, \ldots, x_n) = 0$  has a solution iff *n*-boson's Hamiltonian  $\hat{H} = D(a_1^+a_1, \ldots, a_n^+a_n)$  has the zero ground state. [T.D. Kieu, Int. J. Theor. Phys. 42, 1461 (2003).]

Hilbert's 10th problem  $\longrightarrow$  The ground state of *n*-bosons is uncomputable [W. D. Smith, App. Math. Comp. 178, 184 (2006)]

Whether a quantum system is gapless is not decidable [T. S. Cubitt et al, Nature 528, 207 (2015)].

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## QUANTUM CONTROL OVERVIEW



 $H = H_0 + u(t)V, \qquad P_{i 
ightarrow f}(u) 
ightarrow \max$ 

1980th: V. Belavkin, A. Butkovskiy, P. Brumer, H. Rabitz, S. Rice, Y. Samoilenko, M. Shapiro, D. Tannor, etc.

Now: Extremely high interest. Applications:

- Quantum computing
- Quantum information
- Laser-assisted chemistry, NMR.

Nobel Prize in Physics 2012: S. Haroche and D. Wineland for experimental manipulation of individual quantum systems.

## TYPICAL CONTROL TASKS

State-to-state transfer:

$$\psi_{i} \xrightarrow{u(t)} \psi_{f}, \qquad P_{i \to f} = |\langle \psi_{f}, U_{T} \psi_{i} \rangle|^{2} \to \max$$
  
 $\langle \hat{O}_{T} \rangle = \operatorname{Tr} \Big[ \hat{O} U_{T} \rho_{i} U_{T}^{\dagger} \Big] \to \max$ 

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#### Quantum gate/process generation:

$$\mathbb{I} \xrightarrow{u(t)} W, \qquad |\mathrm{Tr} W^{\dagger} U_{\mathcal{T}}| \to \max$$

#### Examples: W = CNOT, SWAP, Toffoli, ...

# QUANTUM CONTROL: STANDARD FORMULATION

Dynamics:  

$$\frac{d\rho_t^u}{dt} = -i[H_0 + u(t)V, \rho_t^u] + \mathcal{L}(\rho_t^u), \qquad \rho_{t=0}^u = \rho_0$$

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**Objective functional:** 

$${\mathscr F}_O(u) \;\;=\;\; {
m Tr}[{\mathcal O}
ho^u_T] o {
m max}$$

## COHERENT CONTROL AND CONTROLLABILITY

Coherent control

$$\frac{d|\psi_t\rangle}{dt} = -\frac{i}{\hbar} \Big( H_0 + u(t) V \Big) |\psi_t\rangle$$

Controllability

$$|\psi_{\rm i}\rangle \xrightarrow{u(t)} |\psi_{\rm f}\rangle = U_T |\psi_{\rm i}\rangle$$

Controllability criteria:

$$\operatorname{Lie}\{-iH_0,-iV\}\sim\mathfrak{su}(n) \ (\mathrm{or} \ \mathfrak{sp}(n/2))$$

### **KRAUS MAPS**

Kraus map  $\Phi$  — most general transformation of density matrix:

- Linear map  $\Phi: \rho \rightarrow \rho_T$ ;
- Completely positive, i.e.,  $\Phi \otimes \mathbb{I}_K \ge 0$ ;
- Trace preserving, i.e.,  $Tr\Phi(\rho) = Tr\rho$ .

<sup>2</sup>R. Wu, A. Pechen, C. Brif, H. Rabitz, "Controllability of open quantum systems with Kraus-map dynamics", J. Phys. A: Math. Theor., **40**, 5681–5693 (2007).

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Kraus operator-sum representation:

$$\Phi(\rho) = \sum_{k} K_k \rho K_k^+, \qquad \sum_{k} K_k^+ K_k = \mathbb{I}.$$

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For any target state  $\rho_{\rm f}$ , there exist a universally optimal Kraus map  $\Phi_{\rho_{\rm f}}$  such that for any  $\rho$ :  $\Phi_{\rho_{\rm f}}(\rho) = \rho_{\rm f}$ .<sup>2</sup>

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## INCOHERENT CONTROL

General method for coherent and incoherent control of open quantum systems was developed<sup>3</sup>:

$$\frac{d\rho_t}{dt} = -\frac{i}{\hbar}[H_{u(t)}, \rho_t] + \mathcal{L}_{n(t)}(\rho_t),$$

Here u is coherent (e.g., laser field) and n is incoherent (e.g., temperature distribution) control.

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Kraus map:

$$\rho_0 \rightarrow \rho_T = \Phi_{(u,n)}(\rho_0) = \sum_k K_k \rho_0 K_k^+.$$

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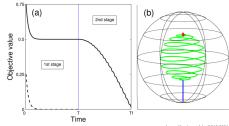
# COMPLETE CONTROLLABILITY

Our general approach with coherent and incoherent controls was used to show<sup>4</sup> that for a generic *N*-level quantum system (for any *N*), there exist coherent u and incoherent n controls, which approximately steer **any initial state to any predefined target state for any** *N*-level system. In other words, open quantum systems are **approximately controllable in the set of all density matrices.** Allows to construct universally optimal Kraus maps.

An example with two levels of calcium atom: moving from the point (0, 0, -1) to the point (0, 0, 0.5) in the Bloch ball. Two stages of the control:

1) using only incoherent control;

2) using only coherent control.



https://arxiv.org/abs/1210.2281

<sup>4</sup>A. Pechen, "Engineering arbitrary pure and mixed quantum states", Phys. Rev. A. **84**, 042106 (2011). (arXiv:1210.2281 [quant-ph])

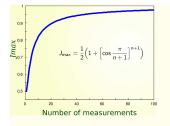
## CONTROL BY QUANTUM MEASUREMENTS

- Belavkin (1983): Theory of controlling quantum systems measured in discrete or continuous time; Wiseman, Milburn (1990): Feedback control. Balachandran, Roy (2000): Quantum anti-Zeno effect.
- Pechen, Ilyn, Shuang, Rabitz (2006):<sup>5</sup> General method

Optimal control by non-selective quantum measurements. Exact analytical solution for a qubit by n measurements:

$$Q_i = \{P_i\}, \quad \mathcal{M}_Q(\rho) = \sum_i P_i \rho P_i$$

$$J = \mathrm{Tr}[\mathcal{OM}_{\mathcal{Q}_n} \dots \mathcal{M}_{\mathcal{Q}_1}(\rho)]$$



Applied by<sup>6</sup>

<sup>5</sup>A. Pechen, N. Il'in, F. Shuang, H. Rabitz, "Quantum control by von Neumann measurements", Phys. Rev. A, **74**, 052102 (2006).

<sup>6</sup>M. S. Blok et al, Nature Physics **10**, 189 (2014); H. W. Wiseman, Quantum control: Squinting at quantum systems, Nature **470**, 178 (2011); etc.

### DIGITIZED QUANTUM CONTROL DISCRETE CONTROLS: In experiments we always have access to a finite number *N* of controls.

<sup>&</sup>lt;sup>7</sup>I.V. Volovich, Number Theory as the Ultimate Physical Theory, p-Adic Numbers, Ultrametric Analysis and Applications. **2**, 77–87 (2010); B. Dragovich, A.Yu. Khrennikov, S.V. Kozyrev, I.V. Volovich, E.I. Zelenov, p-Adic Mathematical Physics: The First 30 Years, p-Adic Numbers Ultrametric Anal.

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RATIONAL NUMBERS IN PHYSICS: All experimental and observational numerical data are rational numbers.<sup>7</sup>  $(O, \rho_0, K_{i,i})$ 

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 ${\it N}$  elementary controls are most generally described by Kraus maps

$$\Phi_i(
ho) = \sum_k K_{i,k} 
ho K_{i,k}^{\dagger}, \qquad \sum_k K_{i,k}^{\dagger} K_{i,k} = \mathbb{I}$$

DQC is to find a control policy (if it exists)  $\mathbf{p} = (p_1, \dots, p_L) \in AP$ (the set of accessible controls) such that

$$\mathcal{F}(\mathbf{p}) := \operatorname{Tr}[O\Phi_{\rho_L}\dots\Phi_{\rho_1}(\rho_0)] = 0$$

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## DQC TO DIOPHANTINE EQUATIONS

Define  

$$\hat{\phi}_k(i) = \sum_{l=1}^N K_{l,k} \prod_{j=1, j \neq l}^N \frac{i-j}{l-j} \text{ such that } \hat{\phi}_k(i) = K_{i,k} \text{ for } 1 \le i \le N$$

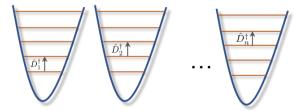
Then  

$$\mathcal{F}(\mathbf{p}) \to \mathscr{F}(\mathbf{p}) = \sum_{k_1, \dots, k_p} \operatorname{Tr} \left( O\left[ \prod_{l=L}^1 \hat{\phi}_{k_l}(p_l) \right] \rho_0 \left[ \prod_{m=L}^1 \hat{\phi}_{k_m}(p_m) \right]^\dagger \right)$$

Solving the DQC is equivalent to solving the Diophantine equation: $\mathscr{F}^2(\mathbf{p}) + \prod_{\mathbf{p}' \in AC} \sum_{k=1}^L (p_k - p_k')^2 = 0$ 

### DIOPHANTINE EQUATIONS TO DQC

$$D(x_1,\ldots,x_n) = 0 \Rightarrow \begin{cases} \rho_0 = |0,\ldots,0\rangle\langle 0,\ldots,0| \\ \Phi_i(\rho) = \hat{D}_i\rho\hat{D}_i^+, \quad \hat{D}_i = e^{a_i^+ - a_i} \\ \hat{O} = -D(a_1,\ldots,a_n)^+D(a_1,\ldots,a_n) \end{cases}$$



#### Hilbert's 10th problem implies unsolvability of DQC!

### EXAMPLE: NP-HARD TWO-BOSON PROBLEM

Deciding the solvability of the Diophantine equation

$$\alpha x_1^2 + \beta x_2 = \gamma$$

with respect to  $x_1$  and  $x_2$  is NP-hard.

Hence NP-hard to find a 2-mode state such that  $\langle \hat{O} \rangle = 0$  with  $\hat{O} = -(\alpha \hat{a}_1^+ \hat{a}_1^+ + \beta \hat{a}_2^+ - \gamma)(\alpha \hat{a}_1 \hat{a}_1 + \beta \hat{a}_2 - \gamma)$ 

## CONCLUSIONS

The negative answer to Hilbert's 10th problem implies that there is no algorithm deciding whether there is a control policy for connecting any given pair of quantum states or, more generally, maximizing expectation of an observable.

$$\psi_{i} \xrightarrow{DQC?} \psi_{f}$$

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